



REMARKS

In this preliminary Amendment, Applicant amended Claims 1-3 and added new Claim 4. Claims 1-3 have been amended to rephrase certain expression. Claim 4 has been added to specify various embodiments of the present invention. The support for the amendment can be found throughout the specification. The specification has been amended to rephrase certain expression and correct certain clerical errors. It is respectfully submitted that no new matter has been introduced by the amended claims and specification. All claims are now present for examination and prompt action toward that end is respectfully solicited.

Respectfully submitted,

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Marked-up Version of Specification Showing Changes Made

TRACTIVE LINEAR RECIPROCATING PROPULSION APPARATUS

5 TECHNICAL FIELDBACKGROUND OF THE INVENTION

FIELD OF THE INVENTION

[0001] The present invention relates to a driving apparatus and, in particular, to a driving apparatus that is characterized by a single endless chain and manually powered linear propulsion, mainly used for securely-sustained non-motorized vehicles or vessels with stable support.

BACKGROUND OF THE INVENTION DESCRIPTION OF PRIOR ART

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[0002] Vehicles and vessels need power drivingto be driven by power. Manually powered devices are commonly used in non-motorized wheel vehicles, among which some have linear reciprocating driving mechanics mechanisms for the purpose of substituting for walking rather than entertaining or exercising. Their structures are complex. Few can be put into actual use.

[0003] Chinese Pat. No. 99108216.8 (CN1275511A) forwarded discloses a bicycle with linear movement of pedaling. It has a toothed rack driving mechanism affixed on a tilted square frame. There are with—two toothed racks in a sliding groove. Depression of either pedal will cause the racks to move, thus draw sprocket wheels and a chain, and transfer the power to a rear driving wheel. A reset gear is used for reset control.

[0004] Other related Related patents are US,A,6129646 (Farmos),; US,A,5236211 (Meguerditchian),; Fr,A,2544052(MICHAUDETG),; US,A,4169609 (Zsmpedro),; and US,A,3891235 (Shelly). All the above-mentioned references disclose open technical designs that employ double a plurality of endless chain mechanisms for alternate propelling in turn. The operating process is simple. However it needs two sets of components to work working alternately. The structure is much very

complicated and there are some difficulties in processing and installation.

[0005] Chinese Pat. No. 99123093.0 (CN1298824A) forwarded discloses a bicycle with a rocking rotatable crank. Its driving mechanism adopts two prime cranks on the left and right for pedal driving. The rear end of the crank is connected with the erank shaft end of a rear wheel with a driven crank linked ing in between, to drive a small sprocket and form a secondary transmission together with a coaxial large sprocket. Finally, and finally the driving power is transmitted to the driving shaft of the rear wheel. It also belongs to approximately—Its method of operation approximates the linear movement of pedaling. But but—with too many transmission links, its efficiency is unavoidably reduceds and reduced efficiency.

[0006] My-Chinese Patent Application (Application No. 01132621.2) discloses "a tractive chain-gripping cycle-bieyele" including the structure of a steel wire rope traction. However, the steel wire rope will curl in the course of small pulley transmitting torque via a small pulley and the curl will affect normal operation of the cycle. In addition, the mechanics mechanism sometimes fails in reversing.

<u>[0007]</u> Obviously, the <u>mechanics-mechanism</u> of <u>the linear pedaling type shall first</u> ensure its smooth <u>and continuous running operation</u>, as well as the convenience of <u>processing during manufacture</u>, especially avoiding <u>overmany-excessive</u> transmission links and <u>reducing reduce</u> idle rung so as to improve transmission efficiency.

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DISCLOSURE-SUMMARY OF THE INVENTION

<u>[0008]</u> The present invention <u>refers-relates</u> to a tractive linear driving apparatus with good integration and structure <u>quality</u> which <u>is applicable to equipping with can be conveniently equipped on manually-powered carriers. The apparatus <u>features—has</u> considerable flexibility in the <u>design—manner</u> of applying force, greater scope for development and design, and <u>comparatively</u> higher transmission efficiency.</u>

[0009] The present invention of tractive linear reciprocating driving apparatus consists of a solid-(main) frame as a fixed member; a movable member having a slipping module a sliding assembly incorporating an engaging a chain-gripping and reversing mechanics mechanism as a movable member; and transmission members of

<u>a</u> single endless chain, <u>and its</u> sprocket wheel and flywheel <u>as a transmission member</u>. The shaft of a flywheel outputs power and forms-achieves mechanical transmission.

[0010] This tractive linear reciprocating driving apparatus comprises—slipping modulea sliding assembly, a slave engaging—chain-gripping and reversing mechanicsmechanism, a flywheel, a driven sprocket, a chain and a main guide column, it has aid apparatus comprising:

[0011] A-a main frame that consists of a guide column, an auxiliary frame column and main frame endplates, the two ends of the frame are affixed with the flywheel and the driven sprocket with a single endless chain installed and linked in between. Its; its-guide column and auxiliary frame column used for directional linear sliding are installed on the side of the plane formed by the endless chain. ring plane; a slipping module A sliding assembly for linear driving and a slave engaging chain-gripping and reversing mechanics is mechanism are installed on the guide column;. The the upper and lower slide bars of the slipping module sliding assembly are mounted on the guide column for slide sliding upwards and downwards along the guide column. The pedals and handpowered rods are used to apply force to butt fixed to plates on both sides of-slipping module the sliding assembly for driving forces to apply thereon;

[0012] It-The apparatus is characterized by:

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<u>mechanism</u> has an engagement means a chain-gripping box located in the plane of the chain ring; the upper and lower slave slide bars connected with the said engagement means is chain-gripping box are mounted on the guide column; engaging toothed bar A chain-gripping tooth plate is provided in the engagement means chain-gripping box. One end of the chain-gripping tooth plate that is subject to force is float-connected to the sliding assembly via a connector. The connector consists of a pull-up rod, a pull-down rod and a connecting rod.—strained end is float connected with slipping module and connecting pieces that consist of pull-up rod, pull down rod and connecting rod; the toothed The tooth plate bar in said engagement means chain-gripping box has two chain-gripping teeth to engage said chain on both directions working—to work jointly with both chain-retaining boards, and chain and

activating alternately with teeth in each direction to engage the chain alternatively.

[0014] 2) Aa reversing compensation means is designed provided for the slave chain-gripping engaging and reversing mechanics mechanism to reverse, the reversing compensation means that comprises comprising a resilient member contacting the front of chain—the tooth of the driven sprocket directly or indirectly in opposite direction, and reserving a space or clearance is left for movement.

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[0015] The said-reversing compensation means is a mobile mechanics mechanism for the purpose of elastic contact located on or beneath the slave sprocket. An _-and_its arm of the reversing compensation means is in contact with may contact the front surface of ehain-the tooth of slave-the driven sprocket elastically under the action of its said-resilient member. To check chain toothstop or prevent the reversing movement of the chain tooth of the driven sprocket, said arm may press the chain tooth under the action of a spring, thus and-realize smooth reverse; and serve as a considerable a certain buffering result.

<u>[0016]</u> The <u>said</u>-reversing compensation means is a modified single-stage flywheel, in which there is a structural member for transmission between <u>a</u> leaf spring and <u>a</u> chain tooth, <u>The</u> leaf spring <u>props-up-supports</u> the rear end of <u>a</u> jack to make it elastically contact firstly <u>with</u> the front of <u>ladder type-trapezoid-shape</u> rackets and then <u>indirectly</u> with the front <u>surface</u> of <u>the</u> chain tooth of <u>an</u> outer hull <u>of the flywheel</u> indirectly.

[0017] The tractive linear reciprocating driving apparatus of this invention has the following vigorous positive effects.:

<u>[0018]</u> 1. Since it adopts <u>a</u> single endless chain structure, the driving apparatus of <u>this</u> the <u>present</u> invention has a more compact structure and <u>more convenience is</u> <u>convenient</u> in <u>processing manufacturing</u> and installation. In application, the whole apparatus can be installed directly in combination with <u>the driving</u> wheel <u>and or an</u> axle of <u>a</u> vehicle or <u>a</u> boat. Linearly applying of force <u>has produces</u> higher efficiency. Even if <u>adding secondary chain drive</u> an additional level of chain transmission is added, the effect is <u>also still</u> quite good.

[0019] 2. This driving apparatus is used mainly for equipping the exercising

apparatus, giving prominence due to the feature of the convenient and natural method of applying force. Since By simultaneously pedaling stepping with his foot and pulling with his hand in operation, a user can obtain a comprehensive exercising exercise effect ean be obtained. It is applicable to a one-man, two-man or multi-man manually-powered vehicle and or boat, as well as communication transportation means or for use in sports competition.;

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[0020] 3. Since slipping module the sliding assembly can suit adapt to the change of different angles of force applied hereto, more designing space thereto, it provides more room for design to meet different seating postures can be obtained to requirements and satisfy various needs in developing applications—application fields and products diversification.;

[0021] 4. Since it—the present apparatus is more suitable for installing in securely sustained a stably supported vehicle or boat, this apparatus it has the features of convenience, safety and comfort. It can be operated even by a user in chair and thus suitable for the old, weak and disabled for relaxation and entertainment.

Brief Description of Drawings BRIEF DESCRIPTION OF THE DRAWINGS

[0022] Fig. 1 is a structural diagram of this the present invention.

[0023] Fig. 2 is a top <u>plan</u> view of the <u>cross section along structure delineated by line A-A.</u>

[0024] Fig. 3 is a structural diagram of the swing toothed bar for chain engagement tooth plate.

[0025] Fig. 4 is a structural diagram of <u>a</u> reversing compensation means.

[0026] Fig. 5 is a structural diagram of directly moved toothed bar for chain engagementa linear moving chain-gripping tooth plate.

[0027] Fig. 6 is a structural view diagram of another type of slipping apparatus sliding assembly.

[0028] Fig. 7 is a structural diagram of reversing compensation means integrated with follower wheel a driven sprocket.

30 [0029] Fig. 8 is a structural schematic diagram of one-man driving tricycle in-of a the

first embodiment.

[0030] Fig. 9 is a top plan view of the embodiment in Fig. 8.

[0031] Fig. 10 is a structural diagram of two-man driving tricycle in of a the-second embodiment.

5 [0032] Fig. 11 is a structural diagram of amphibian bicycle in of a the third embodiment.

[0033] In the above-mentioned drawings, the following reference numbers represent: 1. main frame 2. flywheel 3. chain 4. slipping modules liding assembly 5. pedal 6. handpower-hand-pulling rod 7. guide column 8. driven sprocket sprocket 11. auxiliary frame pillar support 10. reversing-compensator means 12. upper slide bar of slipping module the sliding assembly 13. 11A. guide tongue 14. chain engagement meanschain-gripping box 15. slave pull-up rod chain-gripping engaging and reversing-mechanics mechanism 16. slave upper slide bar 17. chain-retaining board 18. slave lower slide bar 19. chain-engaging toothed barchain-gripping tooth plate 20. lower slide bar of-slipping module the sliding assembly 21. pull-down rod 22. nose of connecting rod 23. front butt plate of slipping module the sliding assembly 24. rear butt plate of slipping module 25. transitional coupling plate 26. bottom plate of chain engagement means 29. 27. short shaft 28. hole to connect rod nose chain-gripping box 30. limit pin 31. chain-engaging teeth 32. chain-engaging chain-gripping teeth 33. groove frame 34. positioning hole 35. tension spring hanging hanged-plate 38. arm shaft 39. damp spring leaf 40. 36. strong compressed spring 37. arm guide groove 41. jogger 42. guide rail of plate column form 43. chute 44. chain tooth 45. leaf spring 46. chute wall 47. compensation clearance 48. mobile erown top block 49. jack spring 50. jack 51. ladder type-trapezoid-shape 53. seat 54. <u>carriage</u>vechicle frame 55. regulating ratchet 52. steel-ball bead 58. follower 56. foot-controlled rudder—masspole 57. driving wheel wheel 59. handlebarhandle bar 60. rod handle 61. connecting rod 62. main wheel (rear) buoy 63. side buoy 64. front buoy 65. impeller propeller

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Detailed Description of the Preferred Embodiment DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

[0034] A better understanding of the invention will be obtained by referring to the accompanying drawings in which:

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[0035] Fig. 1 illustrates a tractive linear reciprocating driving apparatus of given by this invention. It comprises a main frame 1 that consists of, a guide column 7, an auxiliary frame 11 and frame endplates. Connected to one end of the main frame is a flywheel 2 with driving sprocket and to the other another end is a slave sprocket 8 with the same diameter, with a single endless chain installed in between, its. The guide column and the auxiliary frame column are installed on the side of the chain ring plane (backwards in the figure); a slipping module. A sliding assembly 4 and a slave engaging chain-gripping and reversing mechanics mechanism 15 are installed on the guide column:. The main frame may be installed in different ways for the different applications, and can be installed in the appropriate position of a vehicle or a boat through connecting pieces. In this embodiment, the upper and lower slide bars 12, 20 of the slipping module sliding assembly are mounted on the guide column 7 to slide upwards and downwards along the guide column with a guide tongue 11A; pedalPedal 5 and handpower-hand-pulling_rod 6 are affixed to rear butt plate of slipping module—the sliding assembly so as to apply force with foot and hand; respectively. The the chain engagement means gripping box 14 in said slave engaging chain-gripping and reversing mechanics-mechanism operates works in the plane of the chain ring. The chain-gripping box engagement means-14 is connected with the upper and lower slave slide bars 16, 18 and mounted together on the guide column 7. In the The chain-gripping box engagement means 14 is provided with a chain-gripping tooth plate engaging toothed bar-19 that is float-connected by a pull-up rod, a pull-down rod, a nose of a connecting rod and slipping module, to the sliding assembly. The plate follows up the upward or downward movement of slipping module the sliding assembly and controls the activity of chain engaging chain-gripping. In the figure, flywheel 2 -- the driving sprocket to output power, turns the force applied thereto in linear way to shaft torque to operate the driving wheel.

Chain retaining The chain-retaining board 17 with an arc projection to retain the chain is used to limit the position of chain in reversing and guarantee said chain-gripping tooth to engage chain smoothly. Reversing compensation means 10 guarantees the smooth operation of the slave engaging chain-gripping and reversing mechanics mechanism. As shown in the figure, a chain-tensioning device is provided on the sprocket support 9 to adjust the tensioning of the chain by drawing slave sprocket shaft; existing. The conventional structure of a bicycle chain tensioning device is adopted for this embodiment.

bottom plate of the main frame 1, the guide column 7 and the auxiliary frame pillar 11 stand-on both sides, pedal. Pedal 5 is on the left and connecting the front butt plate of slipping module—the sliding assembly 23, 24 and the lower slide bar 20₅. The chain-gripping box engagement means—14 is shown in cross sectional view comprising chain-gripping tooth plate engaging toothed—bar—19, the pull-down rod 21 and a flywheel hidden underneath. Chain The chain-gripping box engagement means—14 connects the upper and lower slave slide bars with transitional coupling plate 25. As shown in the figure, a slave lower slide bar 18 and a lower slide bar of the slipping module—sliding assembly 20 matches with the jaw at a guide tongue 11A on the right. The relation of connection between lower slide bar 20 and two butt plates 23, 24 of slipping module—the sliding assembly incorporating handpower—a hand-pulling rod 6 and a pedal 5 is clearly shown—manifestly.

[0037] Fig. 3 illustrates the structure of the chain-gripping assembly engaging module—in said chain-gripping box engagement means—14. It belongs to a swing chain-gripping engaging—mechanism. Chain A chain-gripping tooth plate engaging toothed—bar—19 is fixed on a bottom plate 26 by a short shaft 27 with a hole 28 to connect the rod nose, when When the tooth plate being drawn upwards and downwards, it swings and reverses the chain—to—engagedirection. There are two chain-gripping engaging—teeth 29, 31 towards both—two opposite directions on said chain-gripping tooth plate engaging toothed—bar—19, together with. The tooth plate and the—chain-retaining board 17 with a chain-retaining arc projection, jointly match

<u>cooperate</u> with chain 3 and <u>are activate</u> alternately <u>activated</u> to perform automatic slave reversing. <u>There 30</u> is a limit pin <u>30</u>.

<u>[0038]</u> The course of slave reversing control is as follows: when <u>the nose</u> of <u>the connecting rod 22</u> is drawn downwards, <u>the chain-gripping engaging</u> teeth 31 will insert in chain-links on the left to carry said chain to go downwards; when drawn upwards, <u>the chain-engaging teeth 31</u> will disengage <u>said the chain and the chain-engaging teeth 29</u> will insert in chain on the right to carry said chain to go upwards. <u>There 30</u> is a limit pin <u>30</u>.

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100391 Fig. 4 illustrates the reversing compensation means installed on the lower part of the slave sprocket on the frame. The hanging hanged-plate 32 of said device is connected with a slave sprocket 8 by a coaxial coupling. An arm 37 is rotatable around the arm axle 38 in the hanging hanged-plate 32. The upper arm end makes straightforward contact with the sprocket teeth. The lower arm end contacts connects a tension spring 35, enabling the upper arm end to contact the front surface of the sprocket tooth front-directly and always activate engage said tooth frontsurface. In reversing of direction, when lower engaging toothed bar the chain-gripping tooth plate 19 below moves towards opposite side, a compensation motion in opposite direction occurs to solve the problem that toothed bar the chain-gripping teeth cannot be inserted in the chain link hole for an instant, and ensures smooth reversing. A strong Strong—compressed spring 36 acts as a buffer in the course of reversing direction. 38 is an arm axle for securing the arm. A positioning Positioning hole 34 is used for adjusting mounting position. 39 is a damp spring leaf. 33 is a fixed groove frame-for securing.

[0040] Fig. 5 illustrates another embodiment of the chain-gripping tooth plate engaging toothed bar with linear directly motion structure. The chain-gripping tooth plate reverses its direction by moving in the Chain engaging toothed bar reverses in guide groove 40. In addition, and joggers 41 are added.

[0041] Fig. 6 illustrates another embodiment of the guide column structure wherein 4 is the sliding assembly slipping module and the slave chain-gripping engaging and reversing mechanism is mechanics are also located therein. 42 is a guide rail of plate column form and 43 is a chute.

[0042] Fig. 7 illustrates a reverse compensation means modified from a single-stage flywheel of a conventional existing bicycle. It can function as a has dual functions of slave sprocket or a and-flywheel. The figure shows a part of the flywheel case in which 44 is a chain tooth in the outskirt of the outer hull that incorporates the trapezoid shape ladder type ratchets 51 in the inner margin of said outer hull 4. A bead, ball path with steel beads balls installed therein is located on both sides of said ratchets.: a A jack 50 (or chaplet) supports props up the inner side inside of said ratchet to force the outer hull only to be in unidirectional rotation. A jack Jack spring 49 (or chaplet spring) forces said jack to prop up <u>and</u> always <u>be</u> in <u>a</u> working condition. A flywheel base and a bottom cover plate form an inner hull installed on the drive shaft. Originally, the flywheel Flywheel originally performs only pure-circular motion. There is no -and-needs no-reversing or compensation problem. To adapt to the reversing function in for-this tractive linear reciprocating driving apparatus, a mobile top block erown 48 is added in a jack groove of the inner hull, which is between the original jack and the fixed block to support the bear said jack, leaving an appropriate clearance (length) 47 for reversing compensation. 46 is the chute wall. A leaf spring 45 is provided behind said mobile top block. erown, The leaf spring bends bending when said jack presses props up said ratchet. When in use, the This compensator uses solid-inner hull is fixed. During reversing, the leaf spring thereof rebounds and presses props up said jack to provide a compensation shift in the opposite direction and in-reversing, carries out the insertion of the teeth of the chain-gripping tooth plate toothed bar-into the chain hole during said shift so as to avoid instant failing of insertion and guarantee a smooth reversing.

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[0043] Figs. 8, 9, 10 and 11 are embodiments of three different applications of this invention.

[0044] Figs. 8 and 9 illustrate structure of <u>a the same</u> one-man manually-powered tricycle that comprises <u>a carriage</u> 54, <u>a regulating wheel</u> 55, <u>a driving wheel</u> 57, <u>a</u> follower wheel 58, <u>a pedal</u> 5, <u>a seat</u> 53, handlebar, <u>as well as the transmission and brake devices. The conventional Traditional mechanism is used for <u>its</u> brake device. The driving Driving wheel is in the <u>right front to the right.</u> The regulating wheel is in the <u>backbehind.</u>, and The driving apparatus is installed on the carriage <u>in front of before</u> the seat. Connected to driving apparatus 1 are the pedal, rod handles 60, handle</u>

bar 59 and <u>a foot-controlled rudder pole mass</u>-56 with <u>double foot</u> positions <u>for two feet</u>. In this embodiment, <u>both hands</u> and feet can be used simultaneously, with one foot controlling direction. On the basis of this embodiment, <u>a two-man manually-powered tricycle can be simply developed simply by widening <u>the carriage</u> and the seat. A conventional <u>Traditional</u>-brake can also be used.</u>

[0045] The following Hereunder explains the working procedure of the tractive linear reciprocating driving apparatus of this invention as shown in the embodiment of said one-man tricycle. ÷

[0046] 1. After riding on seatseated, a user controls regulating wheel with one foot, pedals step—with the other foot, grips the rod handle with one hand to be ready for lifting and holds the handle bar with the other hand.

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[0047] 2. When pedaling by the userstepping, the sliding assembly slipping module 4 goes directly downwards along a straight line, through the driven by nose of the connecting rod 22, drives the pull-down rod 21 to enable enables the chain-gripping engaging teeth 31 of the chain-gripping tooth plate engaging toothed bar 19 to insert into the left chain.; while By continuously applying force by the user, the flywheel 2 operates runs and the driving wheel rotates to drive the tricycle forwards (to the left in the figure).;

<u>[0048]</u> 3. When lifting the rod with hand by the user, the sliding assembly slipping module 4 goes directly upwards along a straight line and through, the pull-up rod 13 is driven to enables chain-gripping engaging teeth 29 of the chain-gripping tooth plate engaging toothed bar 19 to insert in the right chain. By; while continuously applying force by the user, flywheel 2 rotates runs-in original direction and the driving wheel rotates to drive the tricycle forwards (to the left in the figure).

25 [0049] 4. When stopping applying force by the user during pedaling in stepping with his/her foot and lifting with his/her hand, the tricycle keeps running forward by inertia.;

[0050] 5. Repeat above-said operation of stepping with the foot and lifting with the hand, the tricycle keeps running forward.

[0051] Fig. 10 illustrates an embodiment <u>a of another kind of fore-and-aft two-man tricycle</u>. The regulating Regulating wheel 55 is <u>located on designed in the left front</u>.

The ,-driving wheel 57 is on the right side in the middle. The ,-follower rear wheel

58 is provided on the left side of the rear seat., namelyIn another word, the front and rear wheels are on the one same-side and the driving wheel in the middle is on the other side. Two fore-and-aft seats are provided designed. The front seat rider controls the direction and pedals joins stepping with his foot, thus the; connecting rod 61 transmits the imparts driving power to the sliding assembly slipping module. The rear seat rider mainly pulls the rod 60 to apply force. Two riders alternately apply force to jointly drive the tricycle forward. If necessary, the rear seat rider may ean-help in applying force with pedaling stepping. In fact, various two-man embodiments may be designed by utilizing the driving apparatus of this invention, for example, such as the design with type of-rear regulating wheel, the design with double driving apparatus and two-man seats facing in the same direction, the design face to face type with a single or double driving apparatus and two-man seats facing opposite direction, and the design 4 wheel type with single or double driving apparatus having 4 parrallel wheels.

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[0052] Fig. 11 illustrates a structural representation of an amphibious bicycle that incorporates a carriage 54 and wheels, with the driving apparatus 1 tilting in the frontforwards. To suit application in water, an a propeller impeller 65 driven by a chain drive is positioned on the designed in upper front. The propeller 65 has with a draft of 1/4~1/6 of the propeller impeller diameter. Three pairs of buoys are set in the front, middle and rear parts of the carriage on the left and right sides. They are the respectively front buoys 64, side buoys 63 and main (rear) buoys 62, respectively. The side Side-buoys 63 are fixed on both sides of carriage with the supporting litter that incorporate hinges to retract buoys. The buoys at position B, C and D are omitted on in-one side in the figure.

25 [0053] As indicated abioveTo sum up, many products with different structures can be developed utilizing the driving apparatus of this invention. Such arrangements also include: adding an additional secondary chain drive, utilizing leverage or hydraulic transmission, using multiple driving apparatus and different seating postures. Since there may be many varieties, this invention has an excellent future in practical of application.!

What is claimed is:

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1. A tractive Tractive—linear reciprocating driving apparatus having—slipping module (4), slave engaging and reversing mechanics (15), slave sprocket (8), chain (3), guide column (7), in combination, comprising:

<u>a A-frame (1) of the driving apparatus mainly-composed of a by-guide column (7), an auxiliary frame pillar (11) and frame end plates, two opposite both ends of the frame (1)-each equipped with a flywheel (2) and a slave sprocket, respectively (8), with a single endless chain operatively connected therebetween to form a chain ring(3) installed in between, the guide column (7)—used for unidirectional linear sliding slipping—and the auxiliary frame pillar—(11) installed positioned on a plane that is parallel to the endless both sides of chain ring plane; and</u>

<u>a sliding assembly slipping module (4)</u> used for driving and <u>a slave chain-engaging</u> and reversing <u>mechanism mechanics (15)</u> thereof mounted on <u>the guide column</u>, (7);

the sliding assembly having Said slipping module (4) has upper and lower slide bars (12, 20) of slipping module mounted on the said guide column for 7-sliding upwards and downwards along the guide column, at least one pedal (5) and at least one hand-controlled handpower rod (6) used for propulsion mounted on an outside butt plate of the sliding assembly slipping module (4);

wherein:

that are mounted (16, 18) and mounted together on the guide column—7, a chain engaging tooth plate being provided in the strained end thereof is float-connected with the sliding assembly via slipping module and connecting pieces including that eonsist of a pull-up rod (13), a pull-down rod (21) and a nose of a connecting rod (22); there are two chain-engaging toothed bar (19), in cooperation together—with a chain-retaining board having a (17) with chain-retaining arc projection, jointly match with chain 3 and are alternately activated to work;

2) Aa reversing compensation means (10)-used with the slave chain-engaging and reversing mechanism has mechanics having a resilient member that can contact a the

front <u>surface</u> of <u>a</u> chain tooth <u>on the flywheel or the slave sprocket</u> directly or indirectly in inverse direction, and a space or clearance is <u>reserved left</u> for movement.

- 2. The tractive Tractive-linear reciprocating driving apparatus according to claim 1, wherein said reversing compensation means is a resilient contact mobile member mechanics-mounted on or beneath the slave sprocket-(8), the and an arm-(37) under the force of the resilient contact mobile member elastically contacts the front surface of a chain tooth of the slave sprocket-(8).
- 3. The tractive Tractive-linear reciprocating driving apparatus according to claim 1, wherein said reversing compensation means is a modified single-stage flywheel in which there is a structural member for transmission of force between a leaf spring (45) and a chain tooth of the flywheel, the leaf spring pressing a props up the rear end of a jack located near an inner periphery of the flywheel to make it—the jack firstly elastically contact a first the front surface of trapezoid shape ladder type rackets on the inner periphery of the flywheel and then indirectly contact the front surface of a chain tooth on an of-outer hull-indirectly of the flywheel.

4. A tractive linear reciprocating driving apparatus comprising:

a frame of the driving apparatus composed of a guide column in parallel with an auxiliary frame pillar, and two parallel frame end plates in perpendicular position connecting both ends of the guide column and the auxiliary frame pillar to form a generally rectangular shape, two opposite ends of frame each equipped with a flywheel and a slave sprocket, respectively, with a single endless chain operatively connected therebetween to form a chain ring, the guide column used for unidirectional linear sliding and the auxiliary frame pillar positioned on a plane that is parallel to the endless chain ring plane; and

a sliding assembly used for driving and a slave chain-engaging and reversing mechanism thereof mounted on the guide column,

the sliding assembly having upper and lower slide bars mounted on the guide column for sliding along the guide column, at least one pedal and at least one hand-controlled rod used for propulsion mounted on an outside butt plate of the sliding assembly;

wherein:

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- a chain engagement means of said slave chain-engaging and reversing mechanism is positioned in the endless chain ring plane, chain engagement means being connected with upper and lower slave slide bars that are mounted on the guide column, a chain engaging tooth plate being provided in the chain engagement means and one end of the chain engaging tooth plane being is float-connected with the sliding assembly via connecting pieces including a pull-up rod, a pull-down rod and a nose of a connecting rod; two chain-engaging teeth on the chain engaging tooth plate tilted towards two opposite directions and alternatively engaging the endless chain in cooperation with a chain-retaining board having a chain-retaining arc projection;
- a reversing compensation means used with the slave chain-engaging and reversing mechanism has a resilient member that can contact a front surface of a chain tooth on the flywheel or the slave sprocket directly or indirectly in inverse direction, and a space or clearance is reserved for movement.

ABSTRACT

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ABSTRACT OF THE DISCLOSURE

The present invention relates to a linear reciprocating driving apparatus. It includes a sliding assemblyslipping module, a slave chain-engaging and reversing mechanismmechanics, a flying wheel, a driven sprocket, a driving chain, and a guide column. The sliding assembly slipping module is arranged on the framework of the propulsion apparatus to be activated by a rider. Also there is provided a slave chain-engaging and reversing mechanics with compensation means. The propulsion apparatus can obtain satisfying results and high efficiency. The invention can be applied to various manually powered vehicle and watercraft. They are mainly used for communication to substitute walking and physical exercise.